Shanghai Liangxin Electrical Co., Ltd.

NDM3E-630 Product Specification

(IPD-ENG-DEV-T20 A1 2016-09-23)

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|------------------|-----|------|------------|
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| Approved by | 丁飞 | Date | 2021-09-30 |

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| | Revision History | | | | | | | | | | |
|---------|---|-------------------------|----------------|-----------------|-----------------|--|--|--|--|--|--|
| Version | Revision Reason/Content | Implementati on Date | Prepared by | Reviewe d by | Approve d by | | | | | | |
| 0 | Newly added | 2020/10/28 | Sun Lanping | Li Yang | Ding Fei | | | | | | |
| 1 | Update the product appearance picture and product dimension outline drawing | 2021/09/30 | Sun Lanping | Li Vano Li | | | | | | | |
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1. Applicable Scope and Purpose of Circuit Breaker

The NDM3E-630 electronic molded case circuit breaker (hereinafter referred to as circuit breaker) applies to infrequent switching of circuits with the AC 50/60Hz, the working voltage of AC690V and working current of 630A as well as infrequent motor starting. With the overload, short circuit and undervoltage protection functions, the circuit breaker can protect lines and power equipment from damage. The circuit breaker can provide modules with the communication function, which can make the original circuit breaker upgrade to the communication circuit breaker conveniently, thus realizing "Four remotes" functions, namely, remote control, remote adjustment, remote measuring and remote measurement.

2. Product Picture of Circuit Breaker (The picture is for reference only; the



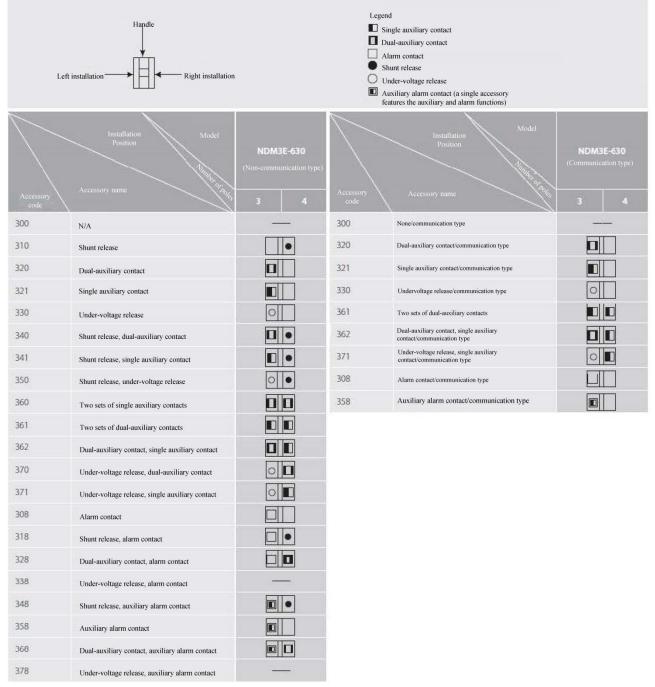
specific kind prevail)

Picture of the Product

3. Specification and Model Description

| $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ |) | | | | | |
|--|--|--|--|--|--|--|
| 1 Enterprise code ND: "Nader" low-voltage apparatus 2 Product code M: Molded case circuit breaker (MCCB) 3 Design SN 3 | | | | | | |
| 2 Product code M: Molded case circuit breaker (MCCB) 3 Design SN 3 | | | | | | |
| 3 Design SN 3 Derived code of | | | | | | |
| Derived code of | | | | | | |
| Derived code of | | | | | | |
| 4 E: Electronic E: Electronic | | | | | | |
| 5 Shell frame level 630 | | | | | | |
| 6 Breaking capacity M: Relatively high breaking type | | | | | | |
| level H: High breaking type | | | | | | |
| No code: Direct handle-operated mode | | | | | | |
| 7 Operation mode P: Motor-operated | | | | | | |
| Z: Rotation handle | | | | | | |
| No code: Basic type intelligent release | | | | | | |
| 8 Derived code of G: Ground protection type intelligent release | | | | | | |
| o T: Communication type intelligent release | T: Communication type intelligent release | | | | | |
| GT: Ground protection communication type intelligent release | : | | | | | |
| 9 Number of poles 3, 4 | | | | | | |
| 10 Accessory code See Table 1 | | | | | | |
| 11 Application code No code: Power distribution type | | | | | | |
| 11 Application code 10 code 1 over antionion type 2: Motor protection type | | | | | | |
| N-pole (neutral C: The N-pole is installed with an overcurrent tripper, and on- | off with | | | | | |
| pole) the other three poles | | | | | | |
| 12 type of the 4P D: The N-pole is installed with an overcurrent tripper, but | D: The N-pole is installed with an overcurrent tripper, but always | | | | | |
| product connected | | | | | | |
| 13 Special use Q: Voltage-check self-reset | | | | | | |
| 14Special function codeI: Non-tripping at the time of alarming | | | | | | |
| 15 Setting current See Table 2 | | | | | | |
| No code: Normal product | | | | | | |
| P: Connection busbar | | | | | | |
| Z1: Rear-plate connection | | | | | | |
| 16 Cabling type Z1: Item plate connection Z2H: Plug-in rear-plate connection | | | | | | |
| Z3H: Integrated plug-in rear-plate connection | | | | | | |
| Z3Q: Integrated plug-in front-plate connection | | | | | | |

Table 1: Comparison Table of Accessory Code:



Note :

1) The first number "3" of the release accessory code represents the intelligent controller with the three-section protection while the last two numbers represent the inner accessory code;

2) Since the communication type requires to use a set of right-side auxiliary contacts, the single auxiliary output is only located on the right side of the above accessory mode.

3)"I" in "32**I" identifies overload alarm without tripping, with output function, and the last two digits ** identify internal accessory code.

4. Main Technical Parameters of Circuit Breaker

Table 2 Main Technical Parameters of Circuit Breaker

| Model | | NDM3E-630 | | | | |
|--|----------------|---------------------------|-------|--------------------------------------|-----|--|
| Rated current of frame | Inm (A) | 630 | | | | |
| Setting current Ir(A) | | | | , 280, 315, 350, , 500, 550, 600, | | |
| Rated insulation voltage | e Ui (AC V) | | | 1000 | | |
| Rated impulse withstan | d voltage Uin | np (V) | | 8000 | | |
| Rated working voltage | Ue (AC V) | | 38 | 0/400/415, 660/ | 690 | |
| Power frequency withs | tand voltage U | J (1min) (V) | | 3500 | | |
| Utilization category | | | | В | | |
| Short-time withstand cu | urrent Icw (kA | A/1s) | 8 | | | |
| Number of poles | | | 4 | | | |
| Breaking capacity level | l | | М | Н | / | |
| Rated limit | AC38 | 0/400/415V | 70 | 100 | 70 | |
| short-circuit breaking capacity Icu (kA) | AC | 660/690V | 20 | / | 20 | |
| Rated operating | AC38 | 0/400/415V | 65 | 70 | 65 | |
| short-circuit breaking capacity Ics (kA) AC660, | | 660/690V | 15 | 15 / | | |
| | Eleo | ctrical life | 7500 | | | |
| Operating performance (times) | Mechanica | Maintainable free life | | 10000 | | |
| I ((((())) | l life | Maintainable life | 20000 | | | |

| | Cable | section | Copper bar size | | |
|-----------------|----------|-------------------------------------|-----------------|---------------------------------|--|
| Rated current A | Quantity | Cross section (mm ²) | Quantity | Dimension (mm ²) | |
| 252 | 1 | 120 | - | _ | |
| 280, 315, 350 | 1 | 185 | - | - | |
| 400 | 1 | 240 | - | - | |
| 450, 500 | 2 | 150 | 2 | 30×5 | |
| 550, 600, 630 | 2 | 185 | 2 | 40×5 | |

4.1 Selection of the circuit breaker connecting bus or cable cross-section area:

| Table 3 Selection of the NDM3E-630 Connecting Bus or Cable Cross-section A | rea |
|--|-----|
|--|-----|

4.2 Tightening Torque of the Circuit Breaker Terminal and Mounting Screw

Table 4 Tightening Torque of the Circuit Breaker Terminal and Mounting Screw

| Model | Thread diameter (mm) | Torque (N·m) |
|-----------|----------------------|--------------|
| | M12 | 28 |
| NDM3E-630 | M6 | 6 |

4.3 Derating factor of temperature change for the circuit breaker

Table 5 Derating Factor Table of Temperature Change for the Circuit Breaker

| Model | Derating factor of product temperature change | | | | | | | | |
|-----------|---|----|----|----|----|----|-------|-------|--|
| NDM3E-630 | Temperature (°C) | 40 | 45 | 50 | 55 | 60 | 65 | 70 | |
| | Derating factor | 1 | 1 | 1 | 1 | 1 | 0.979 | 0.957 | |

Note: 1) When the operating ambient temperature is below + 60° C, the product can be used normally without derating capacity;

2) The above derating factors are measured at the frame current.

4.4 High-altitude derating factor of the circuit breaker

| Elevation (m) | Working current correction coefficient | Maximum working current correction coefficient (V) | Power frequency withstand voltage correction coefficient (V) | Isolation voltage correction coefficient (V) |
|------------------|--|---|---|---|
| 2000 | 1 | 690 | 3500 | 1000 |

Table 6 High-altitude Derating Factor Table of Circuit Breaker

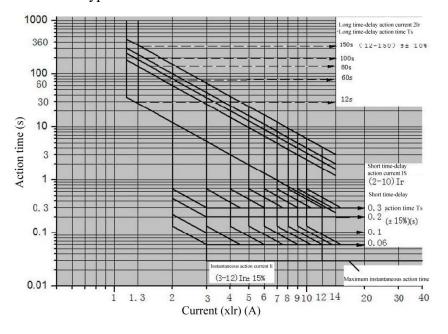
| N | ader e信 | 文件编号:NDT-04543 | 文件版本:1 | | |
|------|---------|----------------|--------|------|--|
| 2500 | 1 | 690 | 3500 | 1000 | |
| 3000 | 0.98 | 620 | 3150 | 900 | |
| 3500 | 0.97 | 580 | 3000 | 850 | |
| 4000 | 0.95 | 550 | 2800 | 810 | |
| 4500 | 0.94 | 520 | 2650 | 770 | |
| 5000 | 0.93 | 500 | 2500 | 730 | |

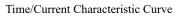
5. Normal Working Environment of Circuit Breaker

- The altitude of the installation site doesn't exceed 2,500m. See the "High-altitude Derating Factor Table of Circuit Breaker" for the derating factor at the altitude;
- 2) The ambient temperature is -35°C ~ + 70°C; the average within 24 h shall not be more than +35°C. If the ambient temperature is higher than +60°C, the user needs to reduce the capacity. See the "Derating Factor Table of Temperature Change for the Circuit Breaker" for the derating factor;
- 3) Its relative humidity at an ambient temperature of +40 °C should not exceed 50%. A higher relative humidity is allowed at a lower temperature. For example, the relative humidity at 20 °C can reach 90%; for frost due to temperature change, the corresponding measures should be taken;
- 4) The product can withstand the effects of wet air, salt mist, oil mist and mould;
- 5) The installation category of the circuit breaker connected to the main loop is: Category III (power distribution and control level), The installation category of the circuit breaker not connected to the main loop is: Category II (load level);
- 6) The pollution level is Level 3;
- The product should be installed in places that are free from explosive media, media corrosive to metal, insulation damaging gas, and conductive dust, which should be also avoided from snow and rain;
- In case of stricter user conditions than the above description, negotiate with the manufacturer.

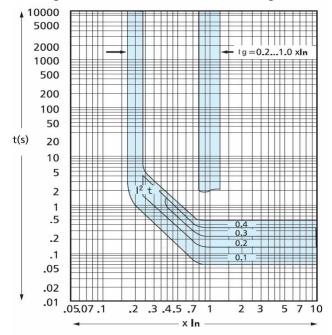
6. Short-circuit Overload Protection Characteristic Curve of Circuit Breaker

6.1 Long time-delay, short time-delay and instantaneous protection characteristic curve of power distribution type

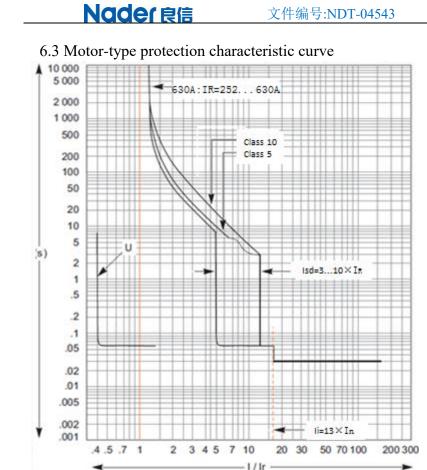




6.2 Ground protection characteristic curve of power distribution type



Ground protection characteristic curve



6.4 Setting value of the intelligent controller

Table 7: Basic type

| | Shell | Current and time parameters | | | | | | | |
|-----------------|---|----------------------------------|-----------------|-------------------|-------------|--------------------|----------------------|-----------------|--------|
| Model | frame level Rated current In(A) | Ir (A) | Tr(s) | Isd(*Ir) | Tsd(s) | Ii(*In) | Ip(*I _R) | Irn(*Ir) | Trn(s) |
| NDM3E-630 3P | 620 | 280, 315 350, 400 450, 500 | 12 60 100 | 2,3, 4 5, 6, 7 | 0.06 0.1 | 3, 4, 5 6, 7, 8 | 0.7, 0.8 0.9, 1.0 | / | / |
| NDM3E-630 4P | 630 | 430, 300 550, 600 630, OFF | 150 0FF | 8, 10, OFF | 0.2 0.3 | 9, 10, 12 14 | Built-in 0.9 | 0.5, 1.0 OFF | Tr |

Table 8: Ground Type

| Tuble 0. Ground Type | | | | | | | | | |
|----------------------|------------------------------------|----------------------|-----------------------------|-----------------------|----------|-----------|----------|----------|-------|
| | Shell frame | | Current and time parameters | | | | | | |
| Model | level Rated current In(A) | Ir(A) | Tr(s) | Isd(*Ir) | Tsd(s) | Ii(*In) | Ip(*IR) | Ig(*In) | Tg(S) |
| | | 280, 315 | 12 | | | 3, 4, 5 | | 0.2, 0.3 | 0.1 |
| NDM3E-63 | (20) | 350, 400 | 60 | 2,3,4 | Built-in | 6, 7, 8 | Built-in | 0.4, 0.5 | 0.2 |
| 0 | 630 | 450, 500 550, 600 | 100 150 | 5, 6, 7 8, 10, OFF | 0.3 | 9, 10, 12 | 0.9 | 0.6, 0.8 | 0.3 |
| | | 630, OFF | OFF | 0, 10, 011 | | 14 | | 1.0, OFF | 0.4 |

Note: For the ground-type 4P product, IRN can't be set with the factory default as 1.0IR in case of no requirements for the order

| | Rated | | Current and time parameters | | | | | | |
|---------------------|------------------------------|-------------------------------|-----------------------------|-----------------------------------|-----------------------|----------------------------|--------------------------|--|--|
| Model | current of frame In(A) | Ir(A) | Tr(s) | Isd(A) | Tsd(s) | Ii(A) | Ip(A) | | |
| NDM3E-63 0 | 630 | 280-630, OFF In step of 1A | 12, 60 100, 150, OFF | 560-6300, OFF In step of 1A | 0.06, 0.1 0.2, 0.3 | 1890-8820 In step of 1A | 196-630 In step of 1A | | |
| | Rated | | | Current and ti | me parameters | | | | |
| Model | current of frame In(A) | | Irn(*Ir) | | Trn(s) | | | | |
| NDM3E-63 0 4P | 630 | 0.5, 1.0, OFF | | Tr | | | | | |

Table 9: Communication Type

Table 10: Ground Communication Type

| | Rated | Current and time parameters | | | | | | | | |
|-----------------|------------------------------------|-------------------------------------|---------------------------|--------------------------------------|---------------------------|-------------------------------|-----------------------------|------------------------------------|----------------------|--|
| Model | current of frame In(A) | Ir (A) | Tr(s) | Isd(A) | Tsd(s) | Ii(A) | Ip(A) | Ig(*In) | Tg(S) | |
| NDM3E-630 | 630 | 280-630, OFF In step of 1A | 12, 60 100, 150 OFF | 560-6300, OFF In step of 1A | 0.06 0.1 0.2 0.3 | 1890-8820 In step of 1A | 196-630 In step of 1A | 126-630 OFF In step of 1A | 0.1, 0.2 0.3, 0.4 | |
| | Rated | | | Cu | rrent and t | ime paramete | ers | | | |
| Model | Model current of frame In(A) | | Irn(| Irn(*Ir) | | | Trn(s) | | | |
| NDM3E-630 4P | 630 | 0.5, 1.0, OFF | | | Tr | | | | | |

Note: 1. When I_R is in the OFF position, the long and short time-delay is closed at the same time; when Isd is in the OFF position, the short time-delay is closed;

2. When the 4P product adopts the basic type, Ip can't be set with the factory default as $0.9I_R$ in case of no requirements for the order;

3. When the product adopts the ground type, Tsd can't be set with the factory default as 0.3s in case of no requirements for the order;

4. When the product adopts the ground type, Ip can't be set with the factory default as $0.9I_R$ in case of no requirements for the order;

5. When the 4P product adopts the ground type, I_{RN} can't be set with the factory default as $1.0I_R$ in case of no requirements for the order;

6. The gear setting of the communication type product needs to be performed by the upper computer, and it is not displayed on the control panel.

Table 11: Motor Protection Type

| | 01 11 0 | | | | | | | |
|-----------|---------------------------------|-------------------------------------|----------|--------------------------------|---------------------------|--|--|--|
| | Shell frame | Current and time parameters | | | | | | |
| Model | level Rated current In(A) | I_{R} (*In) | Class(s) | Isd(*I _R) | Iunbl(%) | | | |
| NDM3E-630 | 630 | 0.4, 0.5, 0.6, 0.7 0.8, 0.9, 1.0 | 4~10 | 3, 4, 5, 6, 7 8, 9, 10, OFF | 10%, 20%, 30% 40%, OFF | | | |

Note: 1. When Isd is in the OFF position, the short time-delay is closed;

2. When Iunbl is in the OFF position, the current imbalance protection is off;

3. The short circuit instantaneous Ii has built-in 13In.

6.5 Protection characteristics of power distribution-type circuit breaker

| | | Over | load long time- | delay prote | ction | Ir, Tr | | |
|-----------------------------|---------------------|-------------|-----------------------------------|---------------------------|--------------------|--------------------------------|---------------|----------------|
| | Setting cu | irrent Ir | | | | See Tabl | le 7 or 8 | |
| TR setting | | | In = 630A | | | | | |
| | | TR set | ting value (s) | 12 | | 60 | 80 | 100 |
| | | v - | ≤1.05Ir | | | >2h ir | naction | |
| A ation footung | (******** | / \ | >1.30Ir | | | <1h a | action | |
| Action features time lim | | t(s |) at 1.5IR | 21.3 | | 106.7 | 142.2 | 177.8 |
| ume mu | lt <i>)</i> | t(s |) at 2.0IR | 12 | | 60 | 80 | 100 |
| | | t(s |) at 6.0Ir | 1.33 | | 6.67 | 11.11 | 16.66 |
| | | t(s |) at 7.2IR | 0.93 | | 4.63 | 6.17 | 7.72 |
| | | Acc | curacy (%) | | | ±1 | .0 | |
| time-delay action | on time | · | action time etting value of th | | | · · | | overload long |
| | | | rcuit short-time | | | - | | |
| | Setting c | urrent Isd | l | | | See Ta | ble 7 or 8 | |
| | Revers lim | | Tsd setting value (s) | 0.06 | | 0.1 | 0.2 | 0.3 |
| A | Isd≤I< | 1.5Isd | t action time (s |) | | t=(1.5Isd/I) ² ×Tsd | | • |
| Action characteristics | | | t action time (s |) 0.06 | | 0.1 | 0.2 | 0.3 |
| characteristics | Fixed tir 1.5Isd | | Returnable time (s) | / | | / | 0.14 | 0.21 |
| | | | Accuracy (%) | ± | 10 (| Inherent | t error± | 20ms) |
| Note: The inver | rse time lin | nit action | curve conforms | to $t = (1.5 \text{Isd})$ | /I) ² × | Гsd | | |
| The r | everse time | e limit is | ON while the fix | ed time limi | it is C | OFF | | |
| t: short-cir | cuit short | time-dela | y action time T | sd: setting v | alue | of the sho | rt-circuit sh | ort time-delay |
| action time | | | | | | | | |
| I: Actual r | unning cur | rent Isd: s | setting value of t | he short-cire | cuit sl | hort time-d | lelay action | current |

| | Table 12 (Conti | nued) Protection C | haracteristics | of li | ntelligent | Release | | |
|---|---|-------------------------|---------------------------------------|--|-----------------------------|-----------------------|------------|--|
| | Sh | ort circuit instan | taneous prote | ectio | n Ii | | | |
| Action char | current Ii | | | See Table 7 | or 8 | | | |
| Action cha | racteristics | Actio | n time | | | <50ms | | |
| | | Neutral wire pro | tection IRN ' | TRN | I | | | |
| | Setting | current Ip | | | | See Table 7 | or 8 | |
| | | TRN act | tion time | | | Tr | | |
| Action char | racteristics | Accura | acy (%) | | | ±10 | | |
| | | Pre-al | arm Ip | | | | | |
| | Setting | current Ip | | | | See Table 7 | or 8 | |
| | | A 1 | ndicator | | The | indicator char | nges to be | |
| characte | eristics | Alarini | Indicator | | constantly on from flashing | | | |
| | | Accura | acy (%) | | ±10 | | | |
| | | Overload indicato | or (maximum | loa | d) | | | |
| | | Current v | alue range | | | 1.15×Ir | | |
| characte | eristics | Overload | Overload indicator | | Constantly on | | | |
| | | Accuracy (%) | | ±10 | | | | |
| | | Ground fault p | rotection Ig, | Tg | | | | |
| 5 | Setting current Ig | 5 | (0.2, 0 | $(0.2, 0.3, 0.4, 0.5, 0.6, 0.8, 1.0) \times I_n + OFF$ | | | | |
| | Reverse time limit | Tg setting value (s) | 0.1 | | 0.2 | 0.3 | 0.4 | |
| Action | Ig≤I∆<2Ig | t action time (s) | | | t =(2Ig | g/I) ² ×Tg | | |
| characteristics | Fixed time | t action time (s) | 0.1 | | 0.2 | 0.3 | 0.4 | |
| $\begin{array}{c c} limit \\ I_{\Delta} \ge 2Ig \end{array} Accuracy (\%) \qquad \pm 10 \end{array}$ | | | | | | | | |
| Note: I: 3P produ | Note: I: 3P product is A/B/C three-phase current vector sum, 4P product is A/B/C/N four-phase current | | | | | | | |
| vector sum. | | | | | | | | |
| Note: The inverse | e time limit actio | n curve conforms t | to $t = (2Ig / I)$ | $^{2}\times T_{2}$ | g | | | |
| t: Action | | | Tg: Setting time of ground protection | | | | | |
| I: Actua | al operating curr | ent | Ig: S | Settir | ig curren | t of ground pr | otection | |

Table 12 (Continued) Protection Characteristics of Intelligent Release

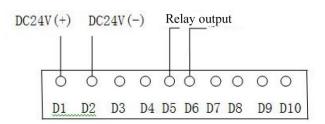
6.6 Motor-type circuit breaker protection characteristics

| Table 13: Motor Protection-type Protection Ch | haracteristics |
|---|----------------|
|---|----------------|

| | Table 13: Motor P | rload pro | | | | 50105 | | |
|--|--|-------------------------------------|----------------------|-----------|----------------------|-------|-----------|-----------|
| Setti | ng current Ir | riouu pro | | | Table 7 o | r 8 | | |
| | Class setting value (s) | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Action | ≤1.05 Ir | | | >2 | 2h inactio | on | | |
| features | >1.20 Ir | | | < | Th action | n | | |
| (reverse time | tr (s) at 1.5 IR | 92.2 | 115.2 | 138.2 | 161.3 | 184.3 | 207.4 | 230.4 |
| limit) | tr (s) at 6.0 IR | 5.8 | 7.2 | 8.6 | 10.1 | 11.5 | 12.9 | 14.4 |
| | t _R (s) at 7.2 IR | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| | Accuracy (%) | | | | ±10 | | | |
| Note: The action curve conforms to t=(7.2) ² ×(I _R) ² ×Class/I ² t: Overload protection action time Class: Setting value of the tripping level time | | | | | | | | |
| | Short circui | | me delay | v protect | ion Isd | | | |
| | Setting current | 1 | | | | | le 7 or 8 | |
| Action | | t ac | tion time | e (s) | 0.06 | | | |
| characteristic s | c Fixed time limit Isd <i (%)<="" accuracy="" td=""><td colspan="4">±10</td></i> | | | | ±10 | | | |
| Current unbalance protection Iunbl | | | | | | | | |
| | Setting v | alue Iunbl | | | 1 | | See Tab | le 7 or 8 |
| | | During startup (< | | | t action time (s) | | 0 | .7 |
| Action | δ≥Iunbl(%) | Class) | | | | | | |
| characteristic s | | During normal operation (≥Class) | | | (9 | S) | 2 | 4 |
| | $\delta \leq \text{Iunbl(\%)}$ | | | | Inaction | | | |
| Note: The calculation of the actual current unbalance conforms to δ=(Imax-Imin)×3×100% / (Ia+Ib+Ic) δ: Percentage value of the actual current unbalance of the three-phase electricity Imax: Maximum current value Imin: Minimum current value Ia: A-phase current value Ib: B-phase current value Ic: C-phase current value | | | | | | | | |
| | (|)pen-pha | | | 1 | | 1 | |
| Action | 1 < 0.41 | Duri | ng startuj Class) | p (< | t action time | | 0 | .7 |
| characteristic s | I<0.4IR | During normal operation (≥Class) | | (s) | | 2 | 4 | |
| | Short circ | - | | · · · · · | on I i | | 1 | |
| Setting current Ii | Short circuit instantaneous protection I i 13In | | | | | | | |
| Action time | < 50 ms | | | | | | | |

6.7 Overload alarm non-tripping signal output module





Wiring Connection Diagram of Output Module

| Terminal code | Connection position | Input/output (IO) | |
|--------------------|----------------------|-------------------|--|
| D1 | Power input DC24V(+) | Input | |
| D2 | Power input DC24V(-) | | |
| D3 | Reserved | Reserved | |
| D4 | Reserved | | |
| D5, D6 | Alarm signal output | Output (DO) | |
| D7, D8, D9, D10 | Reserved | Reserved | |
| L1, L2, L3, L4, L5 | Keserveu | Reserved | |

Table 14: Table of Communication Module Terminals and Roles

Note: 1. Specification of the rated working voltage: DC 24V, allowed range: $\pm 15\%$, power: $\leq 2W$;

2. DO switch output: D5, D6 are dry contact signals, contact capacity: Resistive load DC 30V/5A, AC 270V/3A;

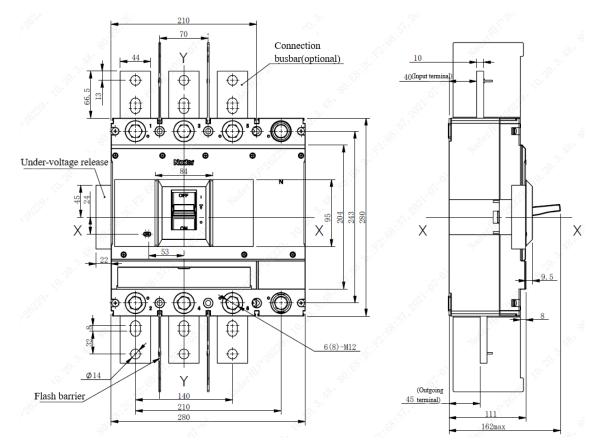
- 3. Closed during overload alarm. Disconnected when there is no overload or non-overload fault;
- 4. Signal output with overload 1.15IR, the shortest maintenance time of this alarm signal is 30s;
- 5. It is necessary to realize the function of overload alarm non-tripping. At this time, the corresponding controller should exit the long time-delay protection (long time-delay TR is set to OFF), otherwise the product will still protect the action;

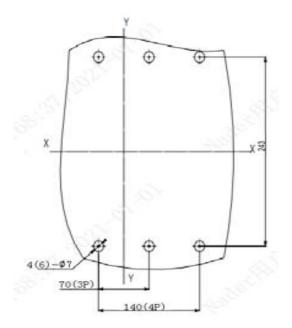
6. When using the overload alarm non-tripping function, it is necessary to eliminate the fault as soon as possible to avoid line heating due to overload for a long time;

7. This accessory can't be used simultaneously with communication accessories.

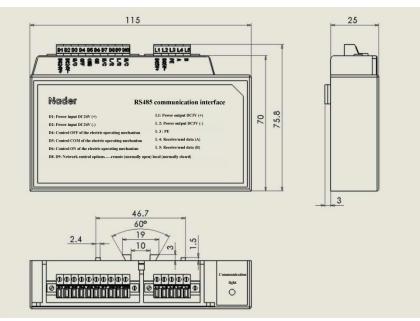
7. Outline and Mounting Hole Dimensions of Circuit Breaker

7.1 Outline and Installation Dimensions of Circuit Breaker





7.2 Installation dimensions of communication backpack



Note: The limit deviation not indicated with the tolerance dimensions is as per GB/T 1804-c.

7.3 Safe mounting distance of circuit breaker

Table 15 Insulation Distance Mounted in the Metal Cabinet (Unit: mm)

| Mounting | A (inlet wire en | d to the cabinet | | | | |
|-----------|------------------|------------------|-----------------------|-----------------------|--|--|
| distance | fac | ce) | B (distance from side | C (outlet wire end to | | |
| Model | With a | Without a | to the cabinet face) | the cabinet face) | | |
| Model | terminal cover | terminal cover | | | | |
| NDM3E-630 | 25 | 120 | 35 | 35 | | |
| | | | | | | |

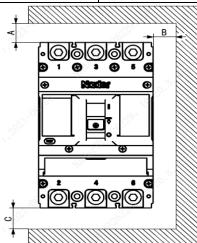


Table 16 Minimum Center Distance between Rowed Circuit Breakers (Unit: mm)

| Model | Width of cir | cuit breaker | Center distance | | |
|-----------|--------------|--------------|-----------------|---------|--|
| Widdei | 3 poles | 4 poles | 3 poles | 4 poles | |
| NDM3E-630 | 210 | 280 | 250 | 320 | |

Note: Check the connected busbar or cable during rowing or stacking of the circuit breaker to ensure that the air

insulation distance won't be reduced.

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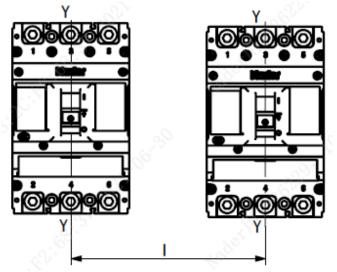


Table 17 Minimum Center Distance between Stacked Circuit Breakers (Unit: mm)

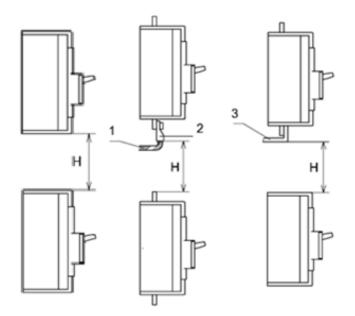
| Model | H (distance of circuit breaker from bottom) | | | | |
|-----------|---|--------------------------|--|--|--|
| Widdei | With a terminal cover | Without a terminal cover | | | |
| NDM3E-630 | 155 | 155 | | | |

Note: 1) Bare cable connection

- 2) Cable insulating connection
- 3) Connection without insulation

Requirements: Check whether the terminal cover or phase partition is assembled properly before

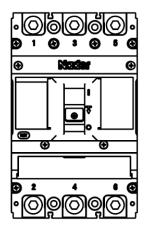
products are energized.

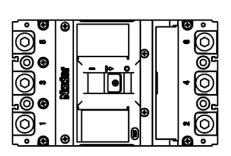


8. Installation Direction of Circuit Breaker

For vertical installation of the product, the gradient between the installation surface and the vertical plane is no more than $\pm 22.5^{\circ}$.

Horizontal installation of the product.





Vertical Installation

Horizontal Installation

9. Packaging and Storage of Circuit Breaker

Minimum packaging quantity: 1 piece/box. The packaged products should be stored in a warehouse with the air ventilation and the relative humidity no more than 80% when the ambient temperature is $-40^{\circ}C \sim +75^{\circ}C$. No acidic alkaline or other corrosive gas exists in the ambient air in the warehouse. Under the conditions above, the storage period shall be no more than three years since the manufacturing date.

10. Installation Direction of Circuit Breaker

| SN | Name | Specification | 3P Quantity/Set | 4P Quantity/Set |
|----|-------------------------------|---------------|--------------------|--------------------|
| 1 | Cross small pan-head screw | M6×95 | 4 | 6 |
| 2 | Hexagon nut | M6 | 4 | 6 |
| 3 | Spring washer | 6 | 4 | 6 |
| 4 | Plain washer | 6 | 8 | 12 |
| 5 | Plug | | 6 | 8 |
| 6 | Phase partition | | 4 | 6 |

11. Circuit Breaker Notes

- Various characteristics and accessories of the circuit breaker are set in the factory. The circuit breaker, tripping unit or other accessories can only be adjusted, installed and maintained by the trained or qualified professionals according to the parameter requirements of the line design;
- 2) Ensure that the power supply is off before installing or removing any device;
- 3) The circuit breaker handle can be located in three positions, indicating three states: on, off and free tripping. When the handle is in the free tripping position, pull the handle in the off direction when the circuit breaker is connected and on.