Shanghai Liangxin Electrical Co., Ltd.

NDM2E-250 Product Specification

(IPD-ENG-DEV-T20 A1 2016-09-23)

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Approved by	1. <i>f</i>	Date	2021-09-28

Nader 良信

	Revision Histo	T		1	
Version	Revision Reason/Content	Implementati on Date	Prepared by	Reviewe d by	Approve d by
0	Newly added	5/8/2020	Wang Hu	Peng Haorang	Hu Qi
1	Update the product appearance picture and product dimension outline drawing	30/9/2021	Sun Lanping	Xu Fuping	Ding Fei

1. Applicable Scope and Purpose of Circuit Breaker

The NDM2E-250 series of electronic molded case circuit breakers (hereinafter referred to as circuit breakers) apply to infrequent switching of circuits with the AC 50Hz, the working voltage of AC400V and working current of 250A as well as infrequent motor starting. With the overload, short circuit and undervoltage protection functions, the circuit breaker can protect lines and power equipment from damage. The NDM2E circuit breaker can provide modules with the communication function, which can make the original circuit breaker upgrade to the communication circuit breaker conveniently, thus realizing "Four remotes" functions, namely, remote control, remote adjustment, remote measuring and remote measurement.

2. Product Picture of Circuit Breaker (The picture is for reference only; the

specific kind prevail)

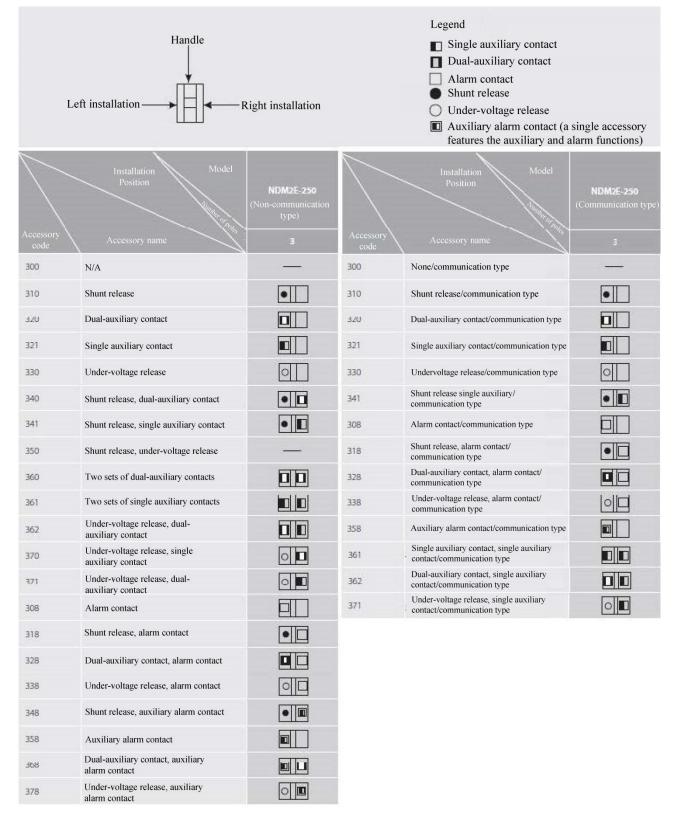


Picture of the Product

3. Specification and Model Description of Circuit Breaker

<u>ND</u> <u>N</u>							
1 2	2 3 4 5	6 7 8 9 10 11 12 13 14					
SN	SN name	NDM2E					
1	Enterprise code	ND: "Nader" low-voltage apparatus					
2	Product code	M: Molded case circuit breaker (MCCB)					
3	Design SN	2					
4	Derived code of the series	E: Electronic					
5	Shell frame level	250					
6	Breaking capacity	M: Relatively high breaking type					
0	level	H: High breaking type					
		No code: Direct handle-operated mode					
7	Operation mode	P: Motor-operated					
		Z: Rotary operation					
		No code: Basic type intelligent release					
8	Derived code of	G: Ground protection type intelligent release					
0	the function	T: Communication type intelligent release					
		GT: Ground protection communication type intelligent release					
9	Number of poles	3					
10	Accessory code	See Table 1					
11	Application code	No code: Power distribution type					
11	Application code	2: Motor protection type					
12	Setting current	See Table 2					
		No code: Normal product					
		P: Connection busbar					
13	Cabling type	Z1: Rear-plate connection					
		Z2H: Plug-in rear-plate connection					
		Z2Q: Plug-in front-plate connection					
		DT: Dedicated for power grid					
14	Other codes	Codes of internal and external accessories:					
14	Other codes	Such as manual operation: CS1-A, electric operation: DC1					
		220V, shunt: AC230V, undervoltage: DC220V					

Table 1: Comparison Table of Accessory Code:



Note :

1) The first number "3" of the release accessory code represents the intelligent controller with the three-section protection while the last two numbers represent the inner accessory code;

2) Since the communication type requires to use a set of right-side auxiliary contacts, the single auxiliary or alarm contact output is only located on the right side of the above accessory mode.

4. Main Technical Parameters of Circuit Breaker

Table 2 Main Technica	l Parameters of	Circuit Breaker
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Model			NDM2E-250		
Rated current of frame	Inm (A)		250		
Setting current Ir(A)	Setting current Ir(A)			80, 200, 225, 250	
Rated insulation voltage Ui (AC V)			80	0	
Rated impulse withstand voltage Uimp (V)			80	00	
Rated working voltage	Rated working voltage Ue (AC V) 400			0	
Power frequency withs	tand voltage U	(1min) (V)	3500		
Utilization category			А		
Rated short-time withstand current Icw (kA/1s)			2.5		
Number of poles			3		
Breaking capacity leve	1		М	Н	
Rated limit short-circuit breaking capacity Icu (kA)	A	C400V	50	85	
Rated operating short-circuit breaking capacity Ics (kA)	A	C400V	50 50		
	Elec	trical life	8000		
Operating performance (times)	Mechanical	Maintainable free life	20000		
	life	Maintainable life	40000		

4.1 Selection of the circuit breaker connecting bus or cable cross-section area

Table 3 Selection of the NDM2E-250 Connecting Bus or Cable Cross-section Area

Rated current (A)	100	125	160	180, 200, 225	250
Wire cross-section area (mm ²)	35	50	70	95	120

4.2 Tightening Torque of the Circuit Breaker Terminal and Mounting Screw

Table 4 Tightening Torque of the Circuit Breaker Terminal and Mounting Screw

Model	Thread diameter (mm)	Torque (N·m)
NDM2E-250	M8	12
NDWIZE-250	M4	2.4

4.3 Derating factor of temperature change for the circuit breaker

Model	Derating factor of product temperature change							
NDM2E-250	Temperature $(^{\circ}\mathbb{C})$	40	45	50	55	60	65	70
	Derating factor	1	1	1	0.976	0.952	0.927	0.902

Note: 1) When the operating ambient temperature is below $+50^{\circ}$ C, the product can be used normally without derating capacity.

2) The above derating factors are measured at the frame current.

4.4 High-altitude derating factor of the circuit breaker

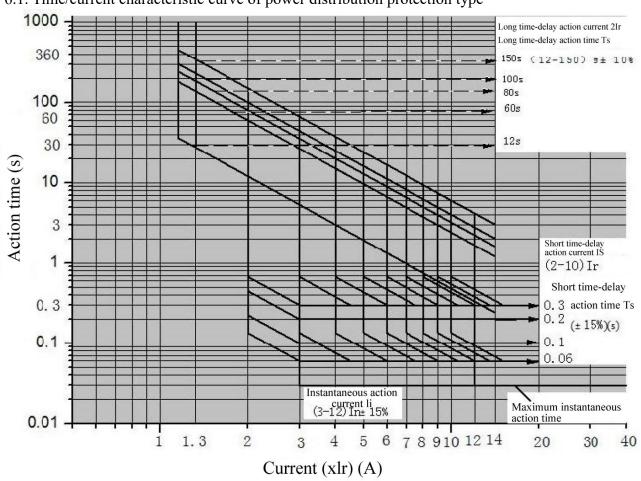
Table 6 High-altitude Derating Factor Table of Circuit Breaker

Elevation (m)	Working current correction coefficient	Power frequency withstand voltage correction coefficient	Isolation voltage correction coefficient
2000	1	3500	800
2500	1	3500	800
3000	0.98	3150	720
3500	0.97	3000	680
4000	0.95	2800	630
4500	0.94	2650	600
5000	0.93	2500	560

5. Normal Working Environment of Circuit Breaker

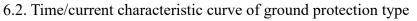
- The altitude of the installation site doesn't exceed 2,500m. See the "High-altitude Derating Factor Table of Circuit Breaker" for the derating factor at the altitude;
- 2) The ambient temperature is -35°C ~ + 70°C; the average within 24 h shall not be more than +35°C. If the ambient temperature is higher than +50°C, the user needs to reduce the capacity. See the "Derating Factor Table of Temperature Change for the Circuit Breaker" for the derating factor;
- 3) Its relative humidity at an ambient temperature of +40 °C should not exceed 50%. A higher relative humidity is allowed at a lower temperature. For example, the relative humidity at 20 °C can reach 90%; for frost due to temperature change, the corresponding measures should be taken;
- 4) The product can withstand the effects of wet air, salt mist, oil mist and mould;
- 5) The installation category of the circuit breaker connected to the main loop is: Category III (power distribution and control level), The installation category of the circuit breaker not connected to the main loop is: Category II (load level);
- 6) The pollution level is Level 3;
- The product should be installed in places that are free from explosive media, media corrosive to metal, insulation damaging gas, and conductive dust, which should be also avoided from snow and rain;
- 8) In case of stricter user conditions than the above description, negotiate with the manufacturer.

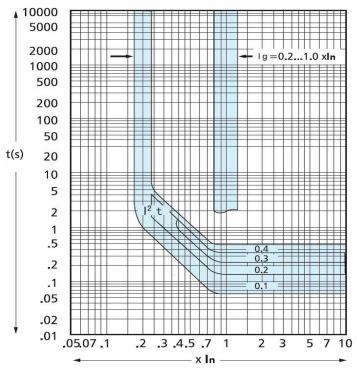
6. Short-circuit Overload Protection Characteristic Curve of Circuit Breaker



6.1. Time/current characteristic curve of power distribution protection type

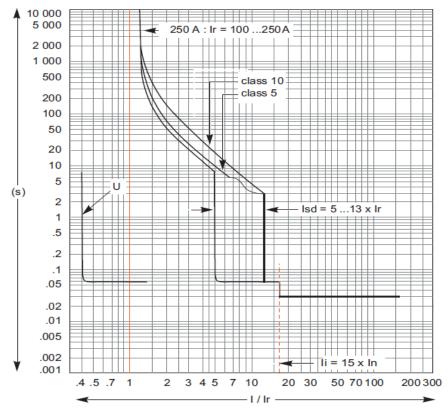
Time/Current Characteristic Curve





Time/Current Characteristic Curve

6.3. Time/current characteristic curve of motor protection type



Time/Current Characteristic Curve

6.4. Setting value of the intelligent controller

6.4.1. Communication-type intelligent controller

Table 7	Communi	cation-type	Intelligent	Controller
Table /	Commun	cation-type	mucingent	Controller

Model	Rated current of	Current and time parameters							
Woder	frame In(A)	Ir(A)	Tr(s)	Isd (*Ir)	Tsd(s)	Ii (*In)	Ip (*Ir)	Ig (*In)	Tg(s)
NDM2E-25 0	250	100, 125 160, 180 200, 225 250, OFF	12 60 80 100	2,3, 4 5, 6, 7 8, 10 OFF	0.06 0.1 0.2 0.3	3, 4, 5 6.4, 7.2 8, 9 10, 12	0.7 0.8 0.9 1.0	0.2, 0.3 0.4, 0.5 0.6, 0.8 1.0, OFF	0.1 0.2 0.3 0.4

Note: When Isd is in the OFF position, the short time-delay is closed.

6.4.2. Non-communication type intelligent controller

Table 8 Communication-type Intelligent Controller

Madal	Rated current of	Current and time parameters							
Model	frame In(A)	Ir(A)	Tr(s)	Isd (*Ir)	Tsd(s)	Ii (*In)	Ip (*Ir)	Ig (*In)	Tg(S)
NDM2E-2 50	250	100, 125 160, 180 200, 225 250, OFF	12 60 80 100	2,3, 4 5, 6, 7 8, 10 OFF	0.06 0.1 0.2 0.3	3, 4, 5 6.4, 7.2 8, 9 10, 12	0.7 0.8 0.9 1.0	0.2, 0.3 0.4, 0.5 0.6, 0.8 1.0, OFF	0.1 0.2 0.3 0.4

Note: When Ir is in the OFF position, the long and short time-delay is closed at the same time; when Isd is in the OFF position, the short time-delay is closed.

6.4.3. Motor protection-type intelligent controller

Table 9 Motor Protection-type Intelligent Controller

	Shell frame level	Current and time parameters					
Model	Rated current In(A)	Ir(*In)	Class(s)	Isd(*Ir)	Iunbl (%)		
NDM2E-250	250	0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.0	4-10	5, 6, 7, 8, 9 10, 11, 12, 13 OFF	10, 20, 30 40, OFF		

Note: 1) When Isd is in the OFF position, the short time-delay is closed;

2) When Iunbl is in the OFF position, the current imbalance protection is off;

3) The short circuit instantaneous Ii has built-in 15In.

6.5. Protection characteristics of power distribution-type circuit breaker

	Ta		rotection Charac				ase	
			rload long time	delay pro	tection			
	Setting cu	irrent Ir					ole 7 or 8	
Triset			ing value (s)			In =	250A	
		Tr setting value (s)		12		60	80	100
		-	≤1.05Ir			>2h i	naction	
Action features	(reverse	2	>1.30Ir			< 1h	action	
time limi	it)	t(s	s) at 1.5Ir	21.3	1	06.7	142.2	177.8
		t(s	at 2.0Ir	12		60	80	100
		t(s	at 7.2Ir	0.93		4.63	6.17	7.72
		Acc	curacy (%)			<u>+</u>	-10	
Note: The actio	n curve co	nforms to	$t = (2Ir/I)^2 \times Tr$					
t: overload	long time	e-delay ac	ction time Tr	setting va	lue of	the overle	oad long time	-delay actior
I: Actual r	unning cur	rent	Ir: setting va	lue of the o	overloa	d long tin	ne-delay actio	n current
	-	Short ci	rcuit short-time	e delay pro	otection	n Isd, Tsd	1	
	Setting c	urrent Isd	[See Ta	able 7 or 8	
	Revers	e time	Tsd setting	0.06	5	0.1	0.2	0.3
Action	limit Isd≤I≤1.5Isd		t action time (s	;)		t=(1.51	sd/I) ² ×Tsd	
characteristics	T ' 1.'		t action time (s	s) 0.06	5	0.1	0.2	0.3
	Fixed tir		Returnable	/		/	0.14	0.21
$1.5 Isd \le I < Ii \qquad Accuracy (\%) \qquad \pm 10$								
Note: The inver	se time lin	nit action	curve conforms	to t=(1.5Is	$d/I)^2 \times I$	Гsd		
The r	everse time	e limit is	ON while the fix	time lin	nit is C	FF		
t: short-cir	cuit short	time-dela	y action time	Fsd: setting	g value	of the sh	ort-circuit sho	ort time-delay
I: Actual r	unning cur	rent	Isd: setting va	lue of the s	short-ci	rcuit shor	t time-delay a	action current

		ued) Protection Cl						
Action	Setting current Ii Action time				See Table 7 or 8			
characteristics						<50ms		
		Pre-ala	arm Ip					
Setting current Ip						See Table 7	or 8	
charact	eristics	Alarm i	ndicator			indicator chai tantly on fron	-	
charact		Accura	acy (%)			±10		
		Overload indicator	r (maxin	num loa	ld)			
		Current value range				1.15×Ir		
charact	eristics	Overload indicator				Constantly on		
		Accuracy (%)			±10			
		Ground fault p	rotection	n Ig, Tg	5			
	Setting current Ig		(0.2, 0.3, 0.4, 0.5, 0.6, 0.8, 1.0)×In+OFF				n+OFF	
	Reverse time	Tg setting value (s)	0.1		0.2	0.3	0.4	
Action	limit Ig≤I∆<2Ig	t action time (s)			t =(2Ig	$t = (2I_g/I)^2 \times T_g$		
characteristics	Fixed time limit	t action time (s)	0.1		0.2	0.3	0.4	
I $\triangle \ge 2Ig$ Accuracy (%) ± 10								
Note: I: 3P produ	cts are A/B/C three	ee-phase current v	ector sur	n				

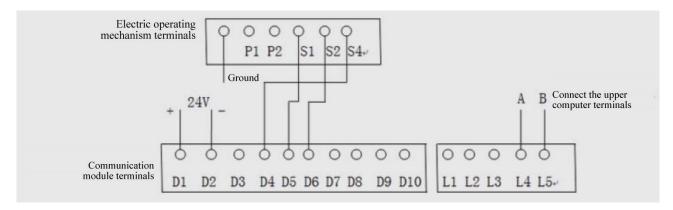
Table 10 (Continued) Protection Characteristics of Intelligent Release

6.6. Protection characteristics of the motor protection-type intelligent release

$\begin{tabular}{ c c c c c c } \hline tr(s) at 6.0 Ir & 5.8 & 7.2 & 8.6 & 10.1 & 11.5 & 12.9 & 14.4 \\ \hline tr(s) at 7.2 Ir & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\ \hline Accuracy (\%) & \pm 10 & \pm 10 & \pm 10 & \hline \\ \hline Accuracy (\%) & \pm 10 & \hline \\ \hline Accuracy (\%) & Class/I^2 & to vertoad protection action time & Class: Setting value of the tripping level time & I: Actual running current & Ir: Setting value of the overload protection action current & Short circuit short-time delay protection Isd & Setting current Isd & Setting current Isd & taction time (s) & 0.06 & \hline \\ \hline Action & Fixed time limit & taction time (s) & 0.06 & \hline \\ \hline Current unbalance protection Iunbl & Set Table 7 or 8 & \hline \\ \hline Current unbalance protection Iunbl & Set Table 7 or 8 & \hline \\ \hline Current unbalance protection Iunbl & Set Table 7 or 8 & \hline \\ \hline Action & Setting value lunbl(\%) & See Table 7 or 8 & \hline \\ \hline Action & Setting value lunbl(\%) & Inaction & \hline \\ \hline Action characteristics & & & & & & & & & & & & & & & & & & &$	Table 1	1 Protection charac					gent releas	se	
Action featuresClass setting value (s)45678910Action features ≤ 1.05 Ir ≥ 2.10 Ir ≤ 1.05 Ir ≥ 2.10 Ir ≤ 1.05 Ir ≥ 1.00 Ir ≤ 1.05 Ir ≤ 1.05 Ir ≥ 1.01 Ir ≤ 1.05 Ir ≥ 1.01 Ir ≤ 1.05 Ir ≤ 1.05 Ir ≥ 1.01 Ir ≤ 1.05 Ir ≥ 1.01 Ir ≤ 1.05 Ir ≤ 1.05 Ir ≥ 1.01 Ir ≤ 1.05 Ir $\leq 1.$			rload pr	otection					
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Setting cur			1	See	Table 7 or 8	8		
Action features (reverse time limit) ≤ 1.05 Ir $>2h$ inaction $T(s)$ at 1.5 Ir 92.2 115.2 138.2 161.3 184.3 207.4 230.4 $T(s)$ at 0.1 Ir 5.8 7.2 8.6 10.1 11.5 12.9 14.4 $T(s)$ at 7.2 Ir 4 5 6 7 8 9 10 Accuracy (%) $T(s)$ at 7.2 Ir 4 5 6 7 8 9 10 Accuracy (%)+10Note: The action curve conforms to $t=(7.2)$ $3c(\Gamma) 3c(Tass)T^2t: Overload protection action timeClass: Setting value of the tripping level timeI: Actual running currentI: Actual running currentIsd<1$			4	5	6	7	8	9	10
$\begin{array}{ c c c c c c c } \mbox{Action features} & \hline > 1.20 \ Ir & \hline < & < \ 1h action \\ \hline tr(s) at 1.5 \ Ir & 92.2 & 115.2 & 138.2 & 161.3 & 184.3 & 207.4 & 230.4 \\ \hline tr(s) at 6.0 \ Ir & 5.8 & 7.2 & 8.6 & 10.1 & 11.5 & 12.9 & 14.4 \\ \hline tr(s) at 7.2 \ Ir & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\ \hline \ Accuracy (\%) & & \pm 10 \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$					>2	h inaction	. <u> </u>		
$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	Action features (reverse time limit)	>1.20 Ir	-1.20 Ir <1				-		
$\frac{\operatorname{tr}(s) \operatorname{at} 7.2 \operatorname{Ir}}{\operatorname{Accuracy}(\%)} \underbrace{4 5 6 7 8 9 10}{\operatorname{Accuracy}(\%)} \underbrace{10}{\operatorname{Accuracy}(\%)} \underbrace{10}{$		tr(s) at 1.5 Ir	92.2	115.2			184.3	207.4	230.4
Accuracy (%) ±10 Note: The action curve conforms to t=(7.2) *(Ir) *Class/1 ² ±10 Note: The action curve conforms to t=(7.2) *(Ir) *Class/1 ² Class: Setting value of the tripping level time I: Actual running current Ir: Setting value of the overload protection action current Short circuit short-time delay protection Isd See Table 7 or 8 Action Fixed time limit taction time (s) 0.06 Current unbalance protection Iunbl See Table 7 or 8 10 Current unbalance protection Iunbl \$ee Table 7 or 8 10 Action Fixed time limit taction time (s) 0.06 Action Fixed time limit 1sd<1		tr(s) at 6.0 Ir	5.8	7.2	8.6	10.1	11.5	12.9	14.4
Note: The action curve conforms to t=(7.2) $\frac{1}{2}(Ir) \frac{3}{2}(Ir) $		tr(s) at 7.2 Ir	4	5	6	7	8	9	10
t: Overload protection action time I: Actual running current I: Action characteristics Action Characteristics Action Characteristics Acti						±10			
I: Actual running currentIr: Setting value of the overload protection action currentShort circuit short-time delay protection IsdSetting current IsdSee Table 7 or 8Action characteristicsSetting current IsdSee Table 7 or 8Current unbalance protection IunblCurrent unbalance protection IunblSetting value Iunbl(%)See Table 7 or 8Current unbalance protection IunblSetting value Iunbl(%)See Table 7 or 8Action characteristicsDuring startup (< Class)0.7Action characteristicsDuring startup (< Class)O OAction characteristicsSetting current unbalance conforms to δ =(Imax-Imin)×3×100% / (Ia+Ib+Ic)Setting value of the actual current unbalance of the three-phase electricity Imax: Maximum current value Ia: A-phase current value Ib: B-phase current value Ib: B-phase current value Ic: C-phase current valueOpen-phase protectionAction characteristicsDuring startup (< Class)O Class)Action characteristicsDuring startup (< Class)O C. Class)Action characteristicsDuring startup (< Class)O C. Class)Action characteristicsDuring startup (< Class) </td <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>									
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Setting current Ii See Table 7 or 8	characteristics	1<0.41f		-		taction	time (s)	2	4
	Short circuit instantaneous protection I i								
Action time $< 50 \text{ ms}$	Setting current Ii	See Table 7 or 8							
	Action time	on time $< 50 \mathrm{ms}$							

Table 11 Protection characteristics of the motor protection-type intelligent release

6.7. Communication module characteristics



Connection diagram of communication module and electric operating mechanism

Terminal code	Connection position	Input/output (IO)	
D1	Power input DC24V(+)	Innut	
D2	Power input DC24V(-)	Input	
D3	Empty		
D4	"OFF" control terminal of the electric operating mechanism		
D5	"COM" control terminal of the electric operating mechanism	Output (DO)	
D6	"ON" control terminal of the electric operating mechanism		
D7	Empty		
D8, D9	Network control options	Input (DI)	
D10	Empty		
L1	Power DC5V(+)	Outrout	
L2	Power DC5V(-)	Output	
L3	PE		
L4	Receive/send data (A)	Input/output	
L5	Receive/send data (B)	Input/output	

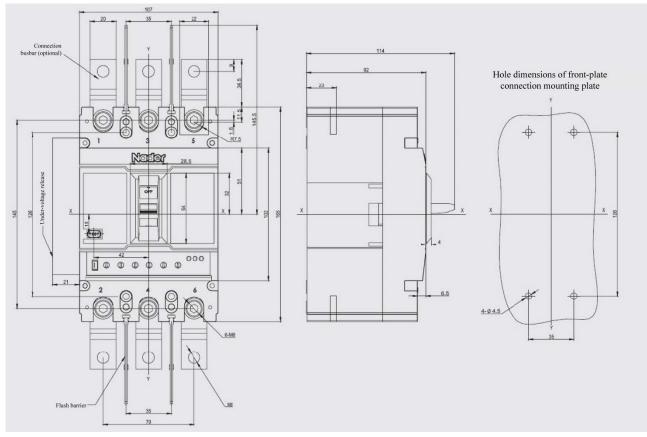
Note: 1) Specification of the rated working voltage: DC 24V, allowed range: $\pm 15\%$, power $\leq 2W$.

2) DI, switch input, input impedance: $\leq 100\Omega$

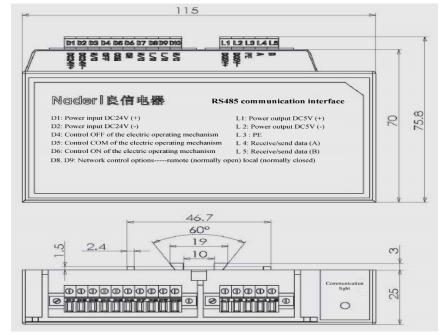
3) DO, switch output, contact capacity: Resistive load DC30V/5A, AC270V/3A.

7. Outline and Mounting Hole Dimensions of Circuit Breaker

7.1 Outline and mounting hole dimensions of circuit breaker



7.2 Installation dimensions of communication module



Note: The limit deviation not indicated with the tolerance dimensions is as per GB/T 1804-c.

7.3 Safe mounting distance of circuit breaker

Table 7 Insulation Distance Mounted in the Metal Cabinet (Unit: mm)

Mounting distance	A (inlet wire end to the cabinet face)			
Model	With a terminal cover	Without a terminal cover	B (distance from side to the cabinet face)	C (outlet wire end to the cabinet face)
NDM2E-250	25	65	30	30

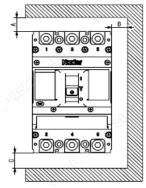


Table 8 Minimum Center Distance between Rowed Circuit Breakers (Unit: mm)

Model	Width of circuit breaker	I Center distance	
Widdel	3 poles	3 poles	
NDM2E-250	107	137	

Note: Check the connected busbar or cable during rowing or stacking of the circuit breaker to ensure that the air insulation distance won't be reduced.

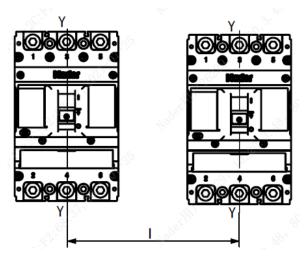


Table	Table 9 Minimum Distance between Stacked Circuit Breakers (Unit: mm)							
Madal	H (distance of circuit breaker from bottom)							
Model	With a terminal cover	Without a terminal cover						
NDM2E-250	90	93						

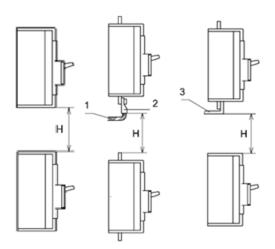
Table 9 Minimum Distance between Stacked Circuit Breakers (Unit: mm)

Note: 1) Bare cable connection

2) Cable insulating connection

3) Connection without insulation

Requirements: Check whether the terminal cover or phase partition is assembled properly before products are energized.

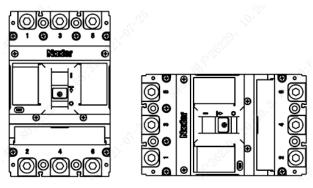


8. Installation Direction of Circuit Breaker

For vertical installation of the product, the gradient between the installation surface and the

vertical plane is no more than $\pm 22.5^{\circ}$.

Horizontal installation of the product.



Vertical Installation Horizontal Installation

9. Packaging and Storage of Circuit Breaker

Minimum packaging quantity: 1 piece/box. The packaged products should be stored in a warehouse with the air ventilation and the relative humidity no more than 80% when the ambient temperature is $-40^{\circ}C \sim +75^{\circ}C$. No acidic alkaline or other corrosive gas exists in the ambient air in the warehouse. Under the conditions above, the storage period shall be no more than three years since the manufacturing date.

SN	Name	Specification	3P Quantity/Set
1	Cross small pan-head screw	M4×45	4
2	Hexagon nut	M4	4
3	Spring washer	4	4
4	Plain washer	4	4
5	Phase partition		4

10. Installation Direction of Circuit Breaker

11. Circuit Breaker Notes

- Various characteristics and accessories of the circuit breaker are set in the factory. The circuit breaker, tripping unit or other accessories can only be adjusted, installed and maintained by the trained or qualified professionals according to the parameter requirements of the line design;
- 2) Ensure that the power supply is off before installing or removing any device;
- 3) The circuit breaker handle can be located in three positions, indicating three states: on, off and free tripping. When the handle is in the free tripping position, pull the handle in the off direction when the circuit breaker is connected and on.